

The background of the slide features a grayscale wireframe model of a human head in profile, facing left. The head is composed of a grid of lines. The background is dark with a pattern of white squares and rectangles, resembling a binary or digital data stream.

Detecting Face with Densely Connected Face Proposal Network

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- **Introduction**
- **Proposed method**
- **Experiments**
- **Summary**

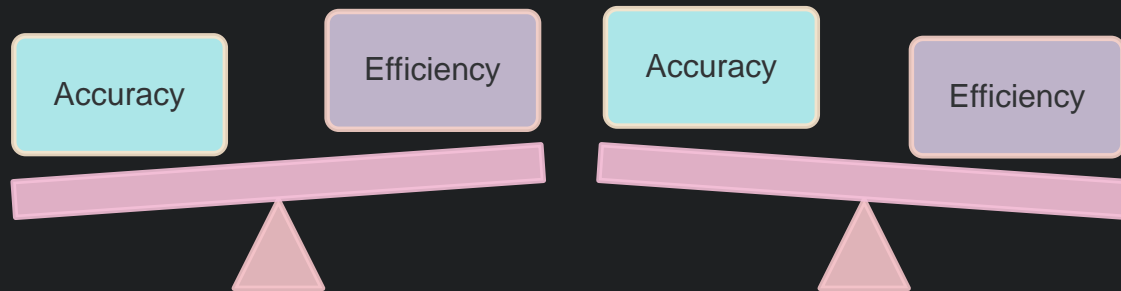
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Motivation

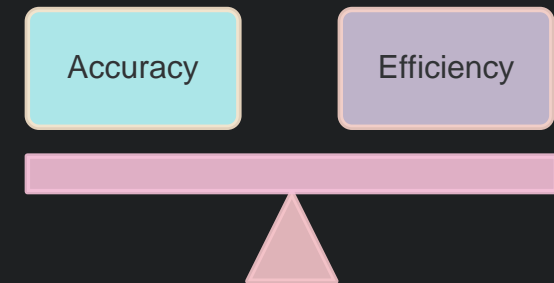
➤ **Dilemma**: Accuracy and efficiency are two conflicting challenges for face detection

- Effective models^[1] tend to be time-consuming
- Efficient models tend to be not robust enough



➤ **Solution**: shrink the input image and focus on detecting small faces

- Trade-off between accuracy and efficiency



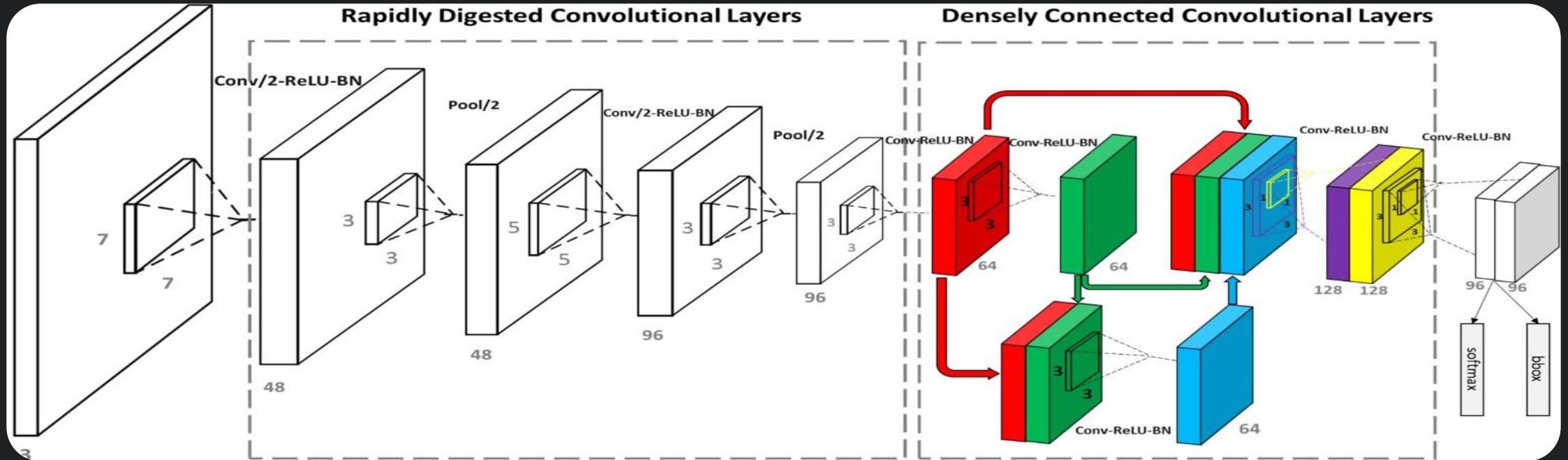
Contributions

- Developing a novel face detector (DCFPN) with high performance as well as CPU real-time speed
- Designing a lightweight-but-powerful network with the consideration of efficiency and accuracy
- Proposing a fair L1 loss and using dense anchor strategy to handle small faces well
- Achieving state-of-the-art performance on common benchmark datasets at the speed of 30 FPS on CPU and 250 FPS on GPU for VGA images

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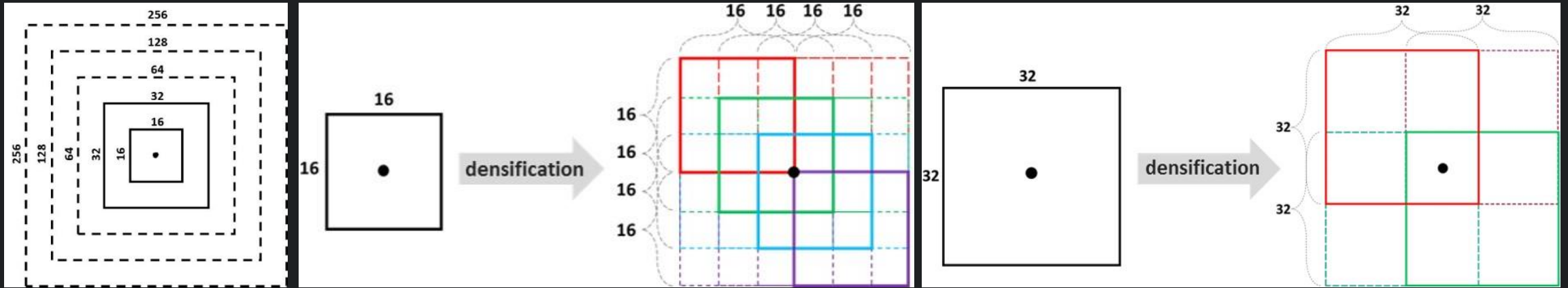
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Architecture



- **Rapidly Digested Convolutional Layers (RDCL)**: quickly reducing spatial size by 16 times with narrow but large convolution kernels to achieve CPU real-time speed
- **Densely Connected Convolutional Layers (DCCL)**: enriching the receptive field to learn visual patterns for different scales of faces, combining coarse-to-fine information to improve the recall rate and precision of detection.

Dense anchor strategy



- **Problem:** the last conv layer has 5 default anchors whose tiling interval are 16 pixels. Comparing with large anchors (64, 128, 256), small anchors (16, 32) are too sparse, which results in low recall rate of small faces.
- **Solution:** dense anchor strategy is proposed by [1] to solve this tiling density imbalance problem. As illustrated in above figure, it uniformly tiles several anchors around the center of one receptive field instead of only tiling one.

Fair L1 loss

- The regression target of Fair L1 loss is as follows:

$$\begin{aligned} t_x &= x - x^a, \quad t_y = y - y^a, \quad t_w = w, \quad t_h = h; \\ t_x^* &= x^* - x^a, \quad t_y^* = y^* - y^a, \quad t_w^* = w^*, \quad t_h^* = h^* \end{aligned}$$

- where x, y, w, h denote center coordinates and width and height, x, x^a, x^* are for predicted box, anchor box, and GT box (likewise for y, w, h). The scale normalization is implemented to have scale-invariance loss value as follows:

$$L_{reg}(t, t^*) = \sum_{j \in \{x, y, w, h\}} fair_{L_1}(t_j - t_j^*), \quad \text{where } fair_{L_1}(z_j) = \begin{cases} |z_j|/w^*, & \text{if } j \in \{x, w\} \\ |z_j|/h^*, & \text{otherwise} \end{cases}$$

- It equally treats small and big face by directly regressing box's relative center coordinate and width and height.

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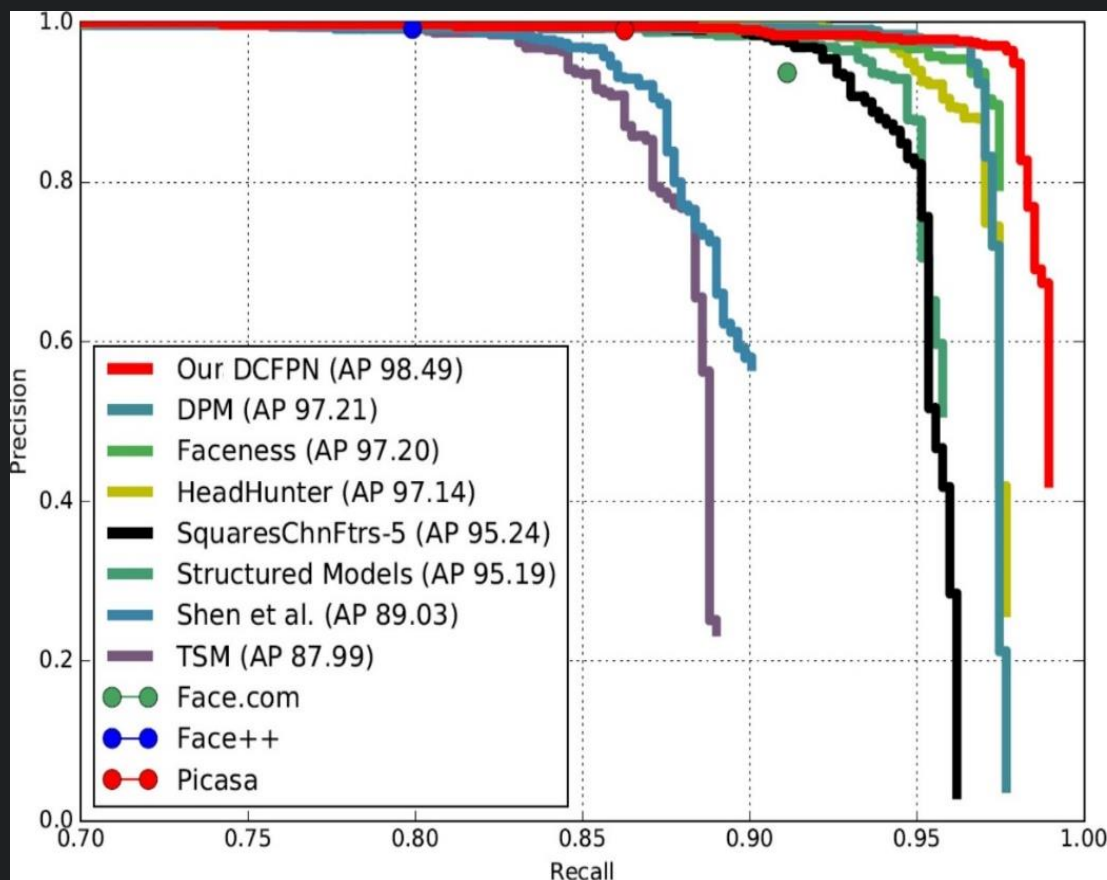
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Model analysis

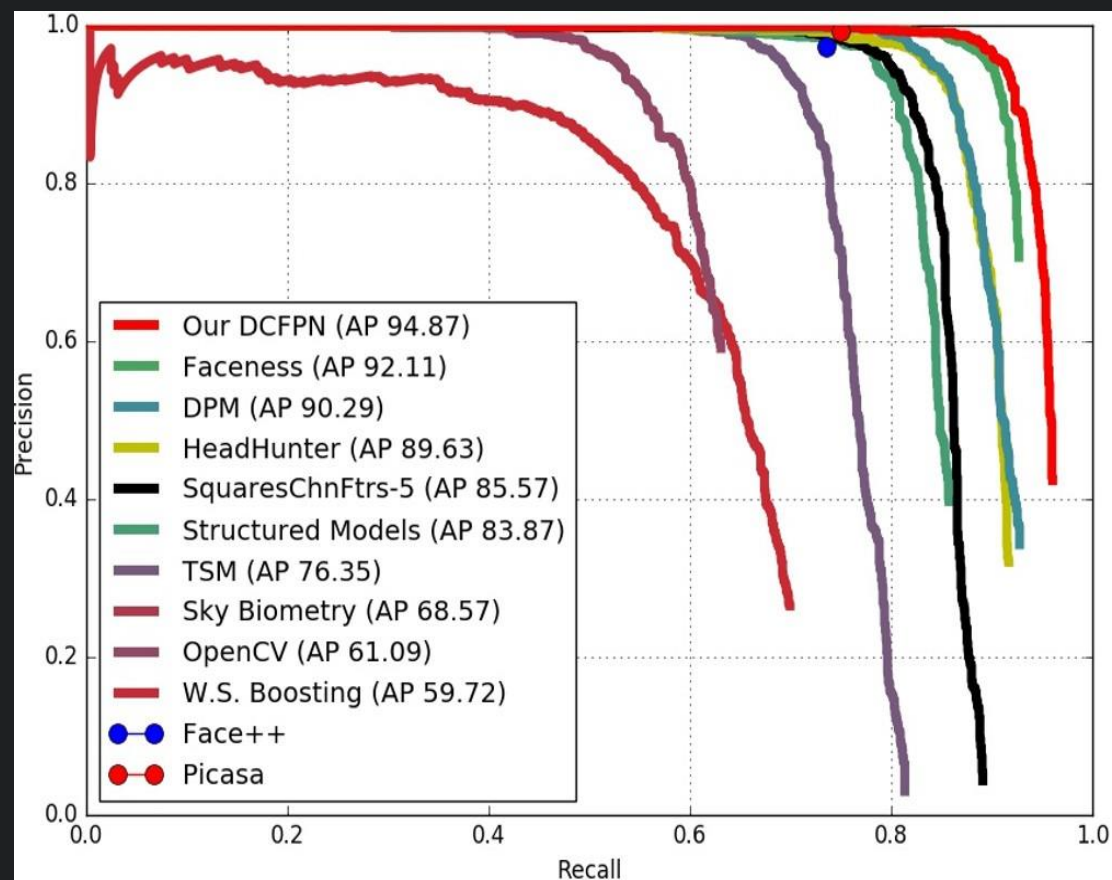
Component	DCFPN			
Designed architecture?	✓	✓	✓	
Dense anchor strategy [2]?	✓	✓		
Fair L1 loss?	✓			
Accuracy (mAP)	95.2	94.5	93.7	93.2

- **Fair L1 loss is promising**: +0.7% owns to locating small faces well
- **Dense anchor strategy is effective**: +0.8% shows the importance of this strategy
- **Designed architecture is crucial**: +0.5% demonstrates the effectiveness of enriching the receptive fields and combining coarse-to-fine information across different layers

Evaluation on benchmark

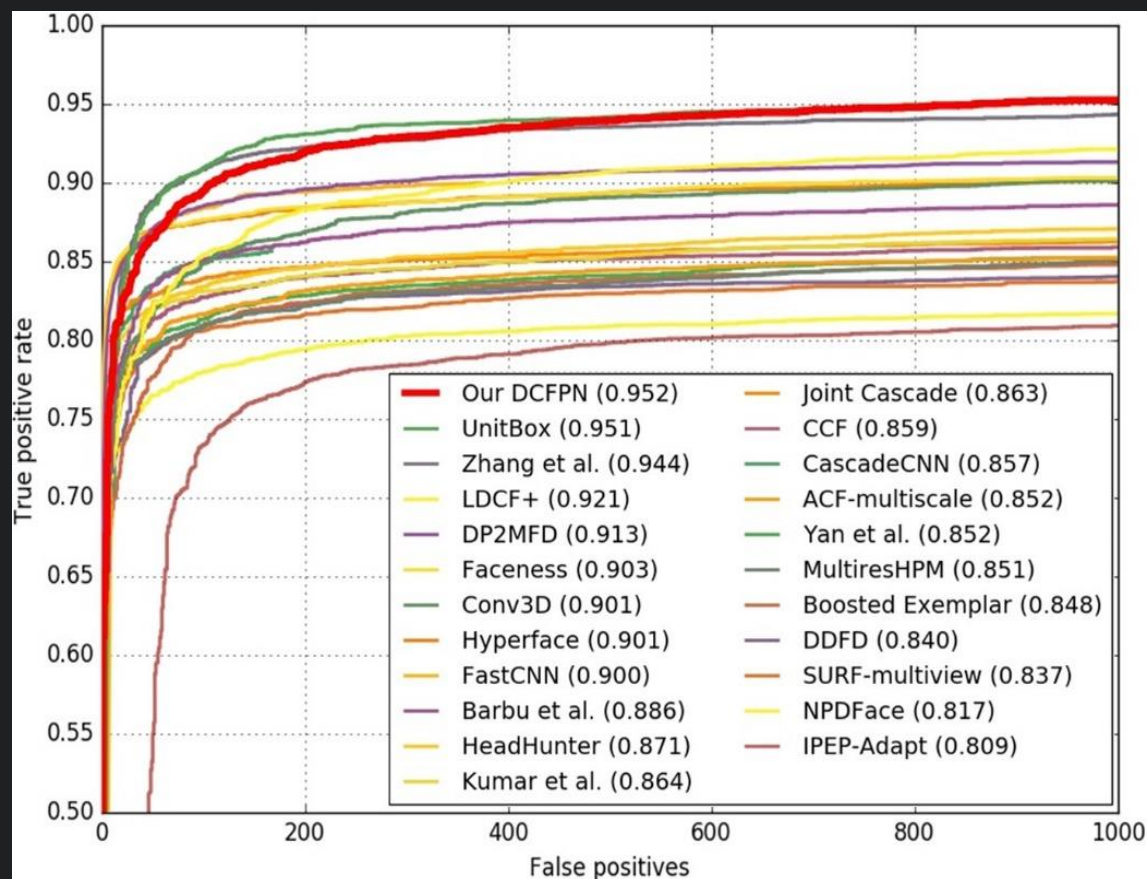


AFW dataset

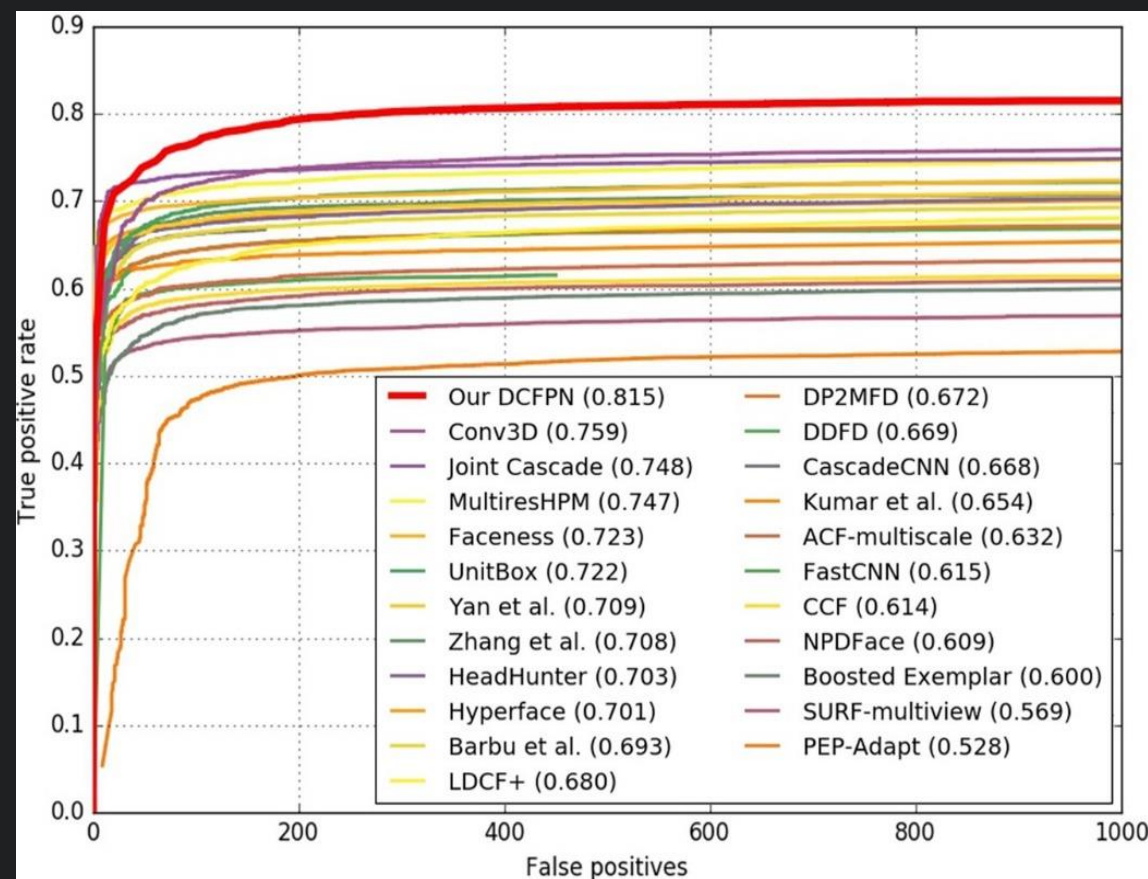


PASCAL face dataset

Evaluation on benchmark



Discontinuous score on Fddb dataset



Continuous score on Fddb dataset

Runtime efficiency

For VGA-resolution images to detect faces ≥ 40 pixels:

CPU

30 FPS on a 2.60GHz CPU

GPU

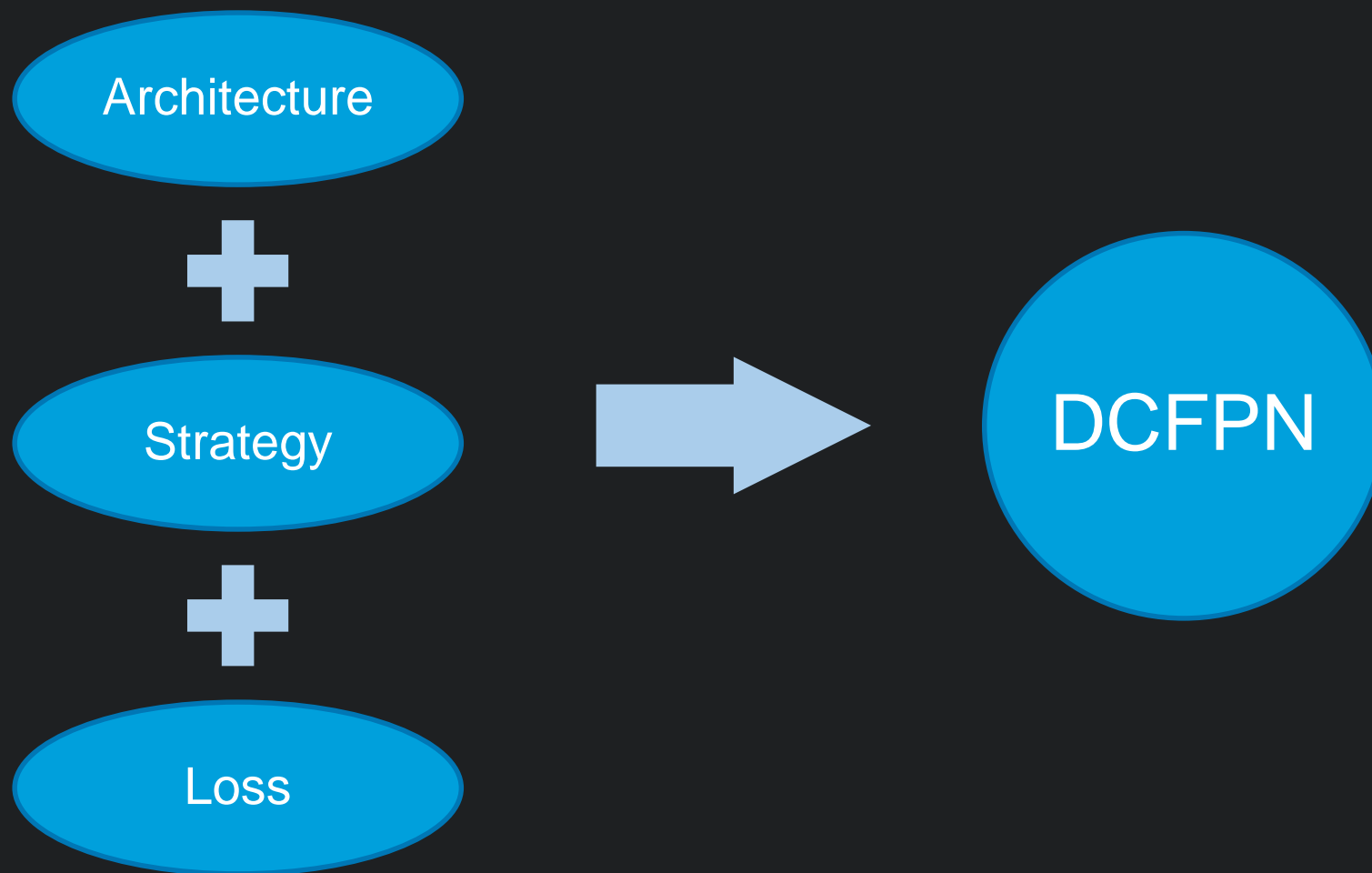
250 FPS using a GPU card

Size

3.2 MB in model size

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Thanks